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by Ruengwit Khwanrit

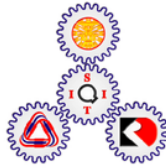
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**ACCURACY COMPARISON AND AUTO-CALIBRATION
ALGORITHM OF PRESENT LOW-COST CURRENT SENSORS
FOR BUILDING ENERGY MONITORING**

BY

RUENGWIT KHWANRIT

**A THESIS SUBMITTED IN PARTIAL FULFILLMENT OF
THE REQUIREMENTS FOR THE DEGREE OF
MASTER OF ENGINEERING (INFORMATION AND
COMMUNICATION TECHNOLOGY FOR EMBEDDED SYSTEMS)
SIRINDHORN INTERNATIONAL INSTITUTE OF TECHNOLOGY
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A Thesis Presented

By

RUENGWIT KHWANRIT

Submitted to

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Abstract

ACCURACY COMPARISON AND AUTO-CALIBRATION ALGORITHM OF PRESENT LOW-COST CURRENT SENSORS FOR BUILDING ENERGY MONITORING

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34

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1

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Reducing energy consumption in building is an important motivation for building energy monitoring and management system. In this work we focus on AC current measurement for small to large appliances such as air conditioners. Today's market has many low-cost AC current sensors that use different technologies and come with different usage convenience. In this research we aim to do a comparison of four low-cost AC current sensor in nowadays market to find the best appropriate current sensor in creating the electrical measurement prototype for implementing in the first phase of Building Energy Management System in SIIT building, Bangkadi campus, Thammasat university, Thailand. We focus to use low cost microcontroller with wifi chip such as ESP8266 and ESP32 for using in the next part of BEMS project to process the input data and send those data to server for monitoring electrical status in SIIT building. We perform the test using AC loads in small steps from zero up to 20 A. Moreover, This research also apply the auto-calibration algorithm to above three analog output current sensor which can help to provide more convenience in calibration and can improve the accuracy of this kind of current sensor.

Keywords: low-cost current sensor, wifi-microcontroller, building energy management system, sensor calibration, measurement accuracy.

Table of Contents

Chapter	Title	Page
	Signature Page	i
	Acknowledgments	ii
	Abstract	iii
	Table of Contents	iv
	List of Figures	vii
	List of Tables	viii
1	Introduction	1
	1.1 Statement of Problem	1
	1.2 Objective of Study	1
	1.3 Significant of Study	2
	1.4 Thesis Organization	2
2	Literature Review	4
	2.1 Low-cost Measurement Component Implementation	4
	2.2 Accuracy Comparison	5
	2.3 Calibration and Linearization	6
3	Components in this work	7
	3.1 Wireless Measurement Node's Components	7
	3.1.1 Wifi-Microcontroller	7
	3.1.1.1 ESP8266	7
	3.1.1.2 ESP32	8
	3.1.2 Current Sensor	10
	3.1.2.1 ACS712	10
	3.1.2.2 WCS1800	10

3.1.2.3	SCT013	10
3.1.2.4	PZEM004T	11
3.2	Calibration and Testing Components	13
3.2.0.1	Reference Meter	13
3.2.0.2	AC Loads	13
3.2.0.3	Keypad	15
4	Current Calculation	16
4.1	Current Sensor's Output	16
4.1.1	ACS712 and WCS1800	16
4.1.2	SCT013	17
4.1.3	PZEM004T	17
4.2	RMS Current Calculation	18
5	Gain Calibration and Accuracy Testing Method	21
5.1	Calibration Method	21
5.1.1	Manual Calibration	21
5.1.2	Auto-Calibration	21
5.1.2.1	First step: Mode Selection	22
5.1.2.2	Second step: Inserting No. of step	23
5.1.2.3	Third step: Inserting I_{rms} and reading $V_{cs,rms}$ value	23
5.1.2.4	Fourth step: Sorting each step's value	24
5.1.2.5	Fifth step: Applying Ordinary Least Square (OLS)	24
5.1.2.6	Sixth step: Recording parameters after auto-calibration process to non-volatile storage	29
5.2	Accuracy Testing Method	29
6	Results and Discussion	31
6.1	Gain Calibration Results	31
6.1.1	Gain Calibration Results: Manual Calibration	31

6.1.2 Gain Calibration Results: Auto-Calibration	32
6.2 Accuracy Results	34
6.2.1 Accuracy Results: Manual Calibration	34
6.2.2 Accuracy Results: Auto-Calibration	36
7 Conclusion	41
7.1 Summary of calibration and testing	41
7.2 Suggesting for future works	42
References	44
Appendices	47
Appendix A: List of publication	48

List of Figures

Figures	Page
3.1 Wemos D1 mini (ESP8266 chip)	7
3.2 Wemos LoLin (ESP32 chip)	8
3.3 ACS712	10
3.4 WCS1800	11
3.5 SCT013	11
3.6 PZEM004T	12
3.7 PX 120 Power meter	13
3.8 Eight 550W mercury vapor lamps	14
3.9 Six 100W incandescent lamps	14
3.10 Keypad	15
4.1 Additional circuit of ACS712 and WCS1800	17
4.2 Additional circuit of SCT013	18
5.1 Mode selection	22
5.2 Diagram of step 2 in auto-calibration operation	23
5.3 Code of bubble sorting	24
5.4 Flowchart of applying OLS step	28
5.5 Code of recording and reading from non-volatile memory	29
6.1 SCT013 manual calibration ($R^2 = 1$)	31
6.2 ACS712 manual calibration ($R^2 = 0.9997$)	32
6.3 WCS1800 manual calibration ($R^2 = 0.9998, 0.9996, 0.9972, 0.9958$)	32
6.4 Example of WCS1800's gains when applied auto-calibration algorithm	34
6.5 Measurement accuracy error of 4 different current sensors	35
6.6 SCT013 accuracy test result	38
6.7 ACS712 accuracy test result	38
6.8 WCS1800 accuracy test result	39

List of Tables

Tables	Page
3.1 ESP8266 and ESP32 details comparison [1]	9
3.2 Current Sensors Properties	12
6.1 Number of gain of current sensors	32
6.2 Example of gain, offset, and boundary of one of WCS1800	34
6.3 Percentage error of fitting error	37
6.4 Percentage error of testing Error	37

Chapter 1

Introduction

1.1 Statement of Problem

Reducing energy consumption in building is an important motivation of building energy management system. Similarly, SIIT building has high power consumption in last many year. Nowadays, SIIT building bangkadi campus has the computer system that allow people to turn on/off air condition in only during class time because they are the main power consumption of the building but this system can not reduce energy much as expect. Now, the president focuses on this problem and want to manage these energy consumption. Because of that, there is an intention to install the energy monitoring and management system. But if SIIT buy the system from commercial company it will cost high budget. Therefore, the building energy management system research is occurred. For the first research of this project aims to build the low cost hardware to monitoring energy consumption of air condition but still has enough performance that can operate correctly, continuously and can send data to the server via SIIT wifi wirelessly. The main component in measurement node is current sensor. So in this work we focus on low-cost AC current measurement sensor in form of module not just a measurement IC chip for easy installation that available in nowadays market. In this research we aim to do a comparison several popular low-cost AC current sensor to find the best appropriate current sensor in creating the electrical measurement prototype for implementing in the first phase of Building Energy Monitoring System in SIIT building.

Moreover, after we have compared those low-cost current sensor. This research also aim to invent the auto-calibration algorithm to analog output current sensor to improve accuracy and provide more conveniently in calibration.

28

1.2 Objective of Study

The main objectives of the research are as follows:

- To find the proper current sensor by comparing measurement accuracy of four popular low-cost current sensor for creating measurement node of SIIT Building energy monitoring system.
- To improve measurement accuracy and convenience in calibration of three analog current sensor by inventing auto-calibration algorithm.

1.3 Significant of Study

This research try to compare the the measurement accuracy of several present low-cost current sensors. The other advantage beside implementing the electrical measurement node for SIIT building can be in many ways as following. Because of none of paper researched about comparing present low-cost current sensors. So this research can be very useful with other researchers who aim to use these low cost component in their research. It does not need to be the building energy monitoring research but it can be any kind of research that involve with these components so they can have information that which low cost component are available in the market nowadays, their price, accuracy, and difficulty in installation. Then they easily can select the appropriate component for their research. Therefore, they can reduce time to learn about all of them just learn some of them which are interesting. Moreover, this research also invented a simple auto-calibration algorithm which help to calibrate analog output current sensor to be more accurate and save much more time than using manual calibration method. This method just use a simple equation and also can be implemented with low-cost microcontroller. So anyone can utilize this algorithm to their own work.

22

1.4 Thesis Organization

The rest of this thesis is organized as follow. In chapter 2, we provide some of literature review about the past low-cost component implementation and their result, accuracy comparison of current sensor, and some of calibration work. Chapter 3 describes about every wireless measurement node's components that we use in this comparison and calibration. Chapter 4 shows current calculation equation of each

current sensor and how microcontroller can calculate RMS current. after that in chapter 5, we describe about accuracy testing method and auto-calibration algorithm and method that we have created. The result and discussion are given in chapter 6. In this chapter we show the calibration and measurement accuracy result from the test. We also discuss about them. Finally, Chapter 7 provides the conclusion of this thesis and gives some recommendation for future work.

Chapter 2

Literature Review

This chapter provides the literature review that related to this thesis. It includes sections on low-cost measurement component implementation, accuracy comparison, and sensor calibration.

2.1 Low-cost Measurement Component Implementation

Several researchs build and Implement low-cost meter for measuring and monitor power consumption status by using low-cost components such as microcontroller and current sensor. Some papers [2, 3, 4, 5, 6, 7, 8] used Arduino board with Atmega microcontroller to process data. Many papers [3, 4, 8, 9] use ESP8266 module to be a wi-fi data transmitter or even microcontroller.

In papers [3, 10], the authors used ACS712 low-cost current sensor, And the others [4, 5, 6] used SCT013 low-cost split core current sensor.

Paper [2], The authors created prototype for monitoring energy called ELIVE device for sensing real-time energy consumption data in a smart home using wi-fi communication. The ELIVE device consists of Arduino microcontroller interface with ESP8266 wi-fi chip and nameless current transducers. The result was compared to BILLION sensor device from Taiwan company and it exposes that ELIVE performs better than BILLION based on the summary statistics.

In [3], This work implements very low-cost wi-fi based digital energy meter by using ESP8266 wi-fi module to communicate between digital meter and web server for monitoring energy consumption and load profile. This system uses Arduino Leonardo Pro to calculate meter parameters and ACS712 current sensor device.

For [4] presented the design and implementation of portable energy meter for any appliances in a residence by using non-invasive current sensor, SCT013. This work uses Arduino nano connect with ESP8266 wi-fi module to transmit real-time acquired data wirelessly to a server then display on a screen and a home energy monitor website. The testing was done by using a variable resistive load and a power analyzer. Average

accuracy was found out to be 92.6 %.

In research [5, 10] made a device that can measure real-time electrical quantities then collect the data in a database system and show the statistics reports on web interface by using BCM2835 (Raspberry Pi) embedded single board to calculation parameter. For [5] also use Arduino to help in data acquisition and uses SCT013 current sensor to sensing current. differently, in the paper [10] uses ACS712 to measure current.

Work [6] proposed a smart plug which can do a real-time energy monitoring and controlled by using an android mobile. This smart plug uses Arduino duemilanove with SCT013 current sensor and ethernet module to upload data to the server. The result shows that this energy consumption monitoring made the consumers to be aware of their wastage electricity and it helps to reduce energy consumption about 15 %.

Similarly in work [9], ⁴⁴ A low-cost wi-fi smart plug is proposed for monitoring power consumption of electrical appliances. The authors also created a web application which can run on smart phone, iPad, and laptop. It used to monitor electrical status and control turing on/off appliance by using relay employed in the single phase. The smart plug uses ESP-WROOM02 (ESP8266 chip) to be the microcontroller and use STPM01 chip to measure energy consumption. The error accuracy is less than 0.5 %.

Also in work [7] also use SCT013 sensor to designed a power meter for measuring single phase power system. The author use two channel ADCs to sampling the voltage and current separately for improving real power accuracy. Moreover, in research [8] implemented PZEM004T sensor, the new electrical measurement sensor, in their work to measured and monitor electrical consumption of a three-phase four power line in a laboratory building and integrated with IoT concept.

ESP32 a new low-cost wi-fi microcontrolerl also very interesting to use in low-cost work. In work [11] proposed a monitoring system of a small photovoltaic power system which designed based on low-cost sensors to measure the current and voltage of battery then this information will be stored in SD card and sent to server via wi-fi.

2.2 Accuracy Comparison

Also, a accuracy comparison of low-cost energy meters is presented in [12]. This work compares accuracy result of 4 nameless different commercially available low-cost

energy meters in 2 test which are power and energy measurement test. The first test, the result shown that low-cost energy meter can perform accordingly to proclaimed accuracy. But for the second test indicated that a good power measurement does not give good energy consumption measurement.

2.3 Calibration and Linearization

In work [13] and [14] presented calibration method for voltage and Hall sensor. Paper [13] applied 1st to 5th polynomial regression to determine the best fitting relationship between input and output of an voltage sensor. They use 2 approaches to calculate voltage which are instantaneous calculation which is the error in measurement is $< 1\%$ and peak-peak voltage method that give the error $< 2.5\%$. And the best result came from third order polynomial regression. Work [14] proposed a novel auto-calibration method which used on-chip actuator to generate 3 reference signals to calculate second order polynomial fitting for sensor's characteristic correction to ensure reliability and accuracy.

Article [15] treats the problem of designing an optimal size for a lookup table (LUT) that applied for sensor linearization. This research proposed a theory for finding the minimum size of a lookup table which does not impact the accuracy of the sensor. Because in any small embedded systems, it just provides a small of memory so the lookup table (LUT) must be reduced to a minimum size.

In work [16] applied a piecewise linear interpolation technique in Field Programmable Gate Array (FPGA) to linearize the a nonlinear characteristic of thermistor for real time application. The temperature in 0-60 C was linearized using 10, 20, and 30 sets of data points. However, the more data points can give the higher accuracy of linearization.

Chapter 3

Components in this work

3.1 Wireless Measurement Node's Components

Wireless Measurement Node consist of 2 things which are wifi-microcontorlelr and curreny sensor. WiFi-microcontroller was used to calculate voltage level from different low-cost current sensors. These mentioned components will be described in this chapter.

3.1.1 Wifi-Microcontroller

Nowadays, there are some of low-cost wifi-microcontroller which already have wifi chip that can process value and send data wirelessly. Also, They are very easy to use. So we intend to use this kind of microcontroller in our testing to calculate value from current sensor. There are 2 popular wifi-microcontrollers in today's market which are ESP8266 and ESP32 (ESP8266 descendant).

3.1.1.1 ESP8266

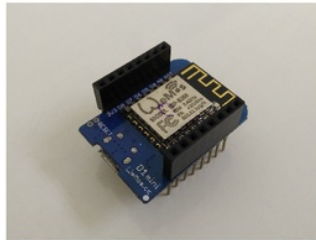


Figure 3.1 Wemos D1 mini (ESP8266 chip)

The vendor of ESP8266 is Espressif (China). Inside this chip contains Tensilica L106 single-core 32-bit microcontroller which runs at 80 MHz (up to 160 MHz) and it has a large amount of flash memory which is 4MB. This chip has 1 ADC port (10-bit). It has deep sleep mode for consuming low power and also has 2 SPI and 1 I2C port. We can use C Arduino language and Arduino IDE to develop it. So we can easily use

this chip same as Arduino. Anyway, this chip has many benefits compared to Arduino board which are the higher cpu speed and flash memory but the limitation is it has only 1 ADC port (Arduino has 6 ports). ESP8266 has several development boards such as Wemos D1 mini, NodeMCU, Witty cloud, ThaiEasyElec's ESPino, ESPDuino etc. The price of development board, for example Wemos D1 mini cost only 185 baht (6 \$). Fig. 3.1 show the Wemos D1 mini board that use ESP8266 wifi-microcontroller chip.

3.1.1.2 ESP32

ESP32 is a new low-cost wifi-microcontroller which is the ESP8266 descendant. It also was created by Espressif (China). Inside this chip contains Xtensa LX6 dual-core 32-bit microcontroller which runs at 160 MHz (up to 240 MHz). It has higher speed than ESP8266 and also has 4MB of flash memory. This chip has 18 ADC (12-bit) ports. It still has deep sleep mode and also has 4 SPI, 2 I2C. We can use C Arduino language and Arduino IDE to develop it. ESP32 has several development boards for example NodeMCU-32S, Wemos LoLin32, DOIT ESP32, Sparkfun ESP32, Adafruit ESP32, and ThaiEasyElec's ESPino32 etc. The price for development board such as Wemos LoLin cost only 330 baht (10.5 \$). Fig. 3.2 show the Wemos LoLin board which use ESP32 (WROOM-32) wifi-microcontroller.





Figure 3.2 Wemos LoLin (ESP32 chip)

From the properties of both low-cost wifi-microcontrollers that mentioned before. We chose ESP32 to use in this work because of we need multi-ADC ports but ESP8266 has only 1 ADC port which means if we want to use ESP8266. We need to use the help from a multiplexer which is consumes much power from switching operation. Another benefit of ESP32 is it has more ADC resolution and more microcontroller speed. And

the price is acceptable. Hence, we selected Wemose LoLin32 development board in this work.

Table 3.1 shows the comparison details for each property of ESP8266 and ESP32 low-cost wifi-microcontroller.

Table 3.1 ESP8266 and ESP32 details comparison [1]

Chip (Module)	ESP8266 (ESP8266-12E)	ESP32 (ESP-WROOM-32)
Picture		
Information :		
CPU	Tensilica L106 32-bit at 80 MHz (up to 160 MHz)	Xtensa Dual-Core 32-bit LX6 at 160/240 MHz
Vendor	Espressif (China)	Espressif (China)
SRAM	36 KB available	520 KB
Flash memory	4 MB (up to 16 MB)	4 MB (up to 64 MB)
Operating voltage	2.5 3.6 V	2.3 3.6 V
Operating current	80 mA (average)	80 mA (average)
Deep sleep current	20 uA	10 uA
Language	C, C++, Lua, Python	C, C++, Lua, Python
Operating temperature	-40 +125 C	-40 +125 C
Wi-Fi	802.11 b/g/n	802.11 b/g/n
Bluetooth	-	4.2 BR/EDR + BLE
Ports :		
UART	2	3
GPIO	17	32
SPI	2	4
I2C	1	2
PWM	-	8
ADC	1 (10-bit)	18 (12-bit)
DAC	-	2 (8-bit)
Starting Price :		
Chip	120 THB (4 \$)	185 THB (6 \$)
Development board	185 THB (6 \$)	330 THB (10.5 \$)

3.1.2 Current Sensor

Current sensor is a device which can measure amount of flowing current and send the output in form of voltage level to microcontroller to calculate the measured current value back. In this work, we selected four low-cost current sensors to compare their accuracy. The details of those current sensors will be described in this section.

3.1.2.1 ACS712

ACS712 is a hall effect current sensor. In market, it has 3 rated current which are 5, 20, and 30. This work will use the highest rated that is 30 A rated current. ACS712 is the ultra low-cost current sensor its price of breakout board is about 85-100 baht (3 \$). This current sensor has some disadvantage that is we need to break the wire that we want to measure current and connect this sensor in series. Fig. 3.3 shows ACS712 current sensor.

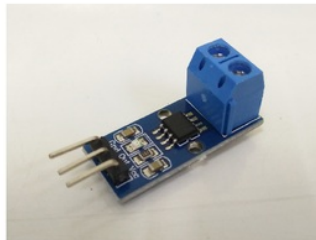


Figure 3.3 ACS712

3.1.2.2 WCS1800

WCS1800 is a hall effect current sensor which has 35 A rated current. Its breakout board price is about 300 - 400 baht (10-12 \$). We can put the wire that we want to measure through the current sensor hole so we do not need to break the circuit and connect sensor in series like ACS712. Fig. 3.4 shows WCS1800 current sensor.

3.1.2.3 SCT013

SCT013 is a split core clamp on current sensor. We can just simply clamp this sensor on the measured wire. This kind of current sensor use induced voltage principle.

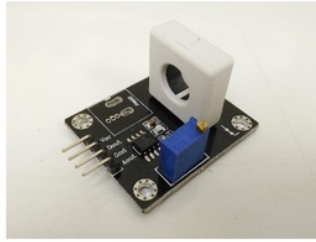


Figure 3.4 WCS1800

The current sensor will act similar to a secondary side of a transformer. Because of that, this kind of sensor can only measure ac current. This current sensor has many rated which are 5, 30, 50, and 100 A_{rms} so we chose the 30 A_{rms} rated current in this work. Its price is about 250 - 400 baht (8-12 \$) depend on the store. Fig. 3.5 shows 30 A SCT013 current sensor.



Figure 3.5 SCT013

3.1.2.4 PZEM004T

PZEM004T is a new low-cost power sensor from China it can measure current, voltage, and power. The current can be measured by putting the wire through the sensor iron core's hole. This sensor can measure current up to 100 A_{rms} . And this price is cheap, about 280 baht (9 \$). Fig. 3.6 shows PZEM004T sensor.

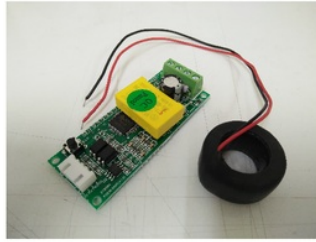


Figure 3.6 PZEM004T

Table 3.2 Current Sensors Properties





Name / Picture	Rated current	DC/AC	Output signal	Installation	Price
ACS712 	$30 A_{DC} / 21 A_{AC}$	DC / AC	Analog Voltage level	Connect sensor in series with wire	85-100 baht (3 \$)
WCS1800 	$35 A_{DC} / 25 A_{AC}$	DC / AC	Analog Voltage level	Put wire through sensors hole	300-400 baht (10-12.5 \$)
SCT013 	$30 A_{AC}$	AC	Analog Voltage level	Split core clamp on wire	250-400 baht (8-12.5 \$)
PZEM004T 	$100 A_{AC}$	AC	UART Serial communication	Put wire through iron cores hole	280 baht (9 \$)

Table 3.2 shows the brief details of above mentioned current sensors which are about

maximum rated current that can be measured by the sensor, what kind of current that the sensor can measure, form of output signal of the sensor, how to install the sensor, and their price.

3.2 Calibration and Testing Components

In this section presents additional components which help us calibrate the sensor and test the current measurement accuracy of the sensors.

3.2.0.1 Reference Meter

First component is reference meter. The current level which will be measured in the calibration operation and in the test will be varied in 0 - 20 A_{rms} range. We use 2 of PX 120 Power meters to show reference current. The PX 120 power meter can measure and result in 2 resolution current but it can only measure current up to 10 A so we separated the electrical circuit into 2 wire and put 2 PX 120 meter at each wire. so we can have input current up to 20 A_{rms} and we put the current sensor to measure the input current before the wire was separated in to 2 line. Fig. 3.7 shows PX 120 power meter.



Figure 3.7 PX 120 Power meter

3.2.0.2 AC Loads

Because the intended application of our current sensors is to measure current consumption by air conditioners, whose biggest size is 36,000 BTU split type which



Figure 3.8 Eight 550W mercury vapor lamps



Figure 3.9 Six 100W incandescent lamps

consumes 18 Amperes maximum, we require our sensor to support current measurement from zero to 20 A.

During calibration of the sensors, we need to generate current draw at multiple values. To do this we build an inexpensive variable dummy resistive load consisted of incandescent and street light bulbs, shown in Fig. 3.8 and Fig. 3.9 , as following:

- Six 100W incandescent bulbs ("small" bulbs)
- Eight 550W mercury vapor bulbs ("large" bulbs) used for street lighting

Each of the small and large bulbs consumes 0.435 A and a constant level between 2.1 – 2.5 A, respectively. These bulbs consume constant power after the initial warm-up period (less than 10 minutes). With these bulbs, we have 63 different combinations of the bulbs which means 63 different current steps. For example, if each large bulb

consumes 2.5A, then the current steps are 0, 0.435 A (1 small bulb), 0.87 A (2 small bulbs), 1.30 (3 small), 1.74 (4 small), 2.18 (5 small), 2.5 (1 large bulb), 2.61 (6 small), 2.94 (1 small + 1 large), and so on until 22.6 A (6 small + 8 large bulbs). But each of large bulb might consume current less than 2.5 A. So the final current is 19.6 A. Since the large bulbs cannot be immediately turned on after turned off, each calibration must start with all large bulbs on. In future, we can add in relays to control turning on/off these bulbs from the microcontroller. This will allow fully automatic data collection for calibration.

3.2.0.3 Keypad

We used a keypad to help us do the auto-calibration process by inserting number of point in 2 digits in and inserting measured I_{rms} in 4 digits at each value to microcontroller. For example, If loads consume current 7.42 A then we insert 0, 7, 4, and 2 to the microcontroller by using this keypad.



Figure 3.10 Keypad

Chapter 4

Current Calculation

In this section, we describe about output's equation of each kind of the current sensor and how to calculate I_{rms} by using microcontroller.

4.1 Current Sensor's Output

4.1.1 ACS712 and WCS1800

Both ACS712 and WCS1800 are hall effect current sensors which give analog voltage level output that is a linear function of the instantaneous current as

$$v_{cs}(t) = \alpha(t) + \beta * i(t) \quad (4.1)$$

where

$v_{cs}(t)$ is the instantaneous sensor output voltage

$i(t)$ is the measured instantaneous current

β is called the gain

$\alpha(t)$ is the offset

The $\alpha(t)$ is used to make the sensor output voltage v_{cs} to be non-negative value since the sensor output voltage can be negative or positive. Hence, the typical value of the offset is 2.5 V. The offset is added internally by the sensor. However, the offset may vary with time due to the variation in the power supply. Since the output voltage of sensors ranges between 0.8 to 4.2 V but ESP32 only support input between 0 to 3.3 V, we need to use a voltage divider to scale down the sensor output voltage, by a factor of 2/3, to be in the proper range of 0.54 - 2.8 V for the MCU. For convenience, we change out notation a bit where we redefine $v_{cs}(t)$ in (4.1) as the instantaneous sensor voltage at the output of the voltage divider. This makes the typical value of the offset $\alpha(t)$ to be $2.5(2/3) = 1.67$ V.

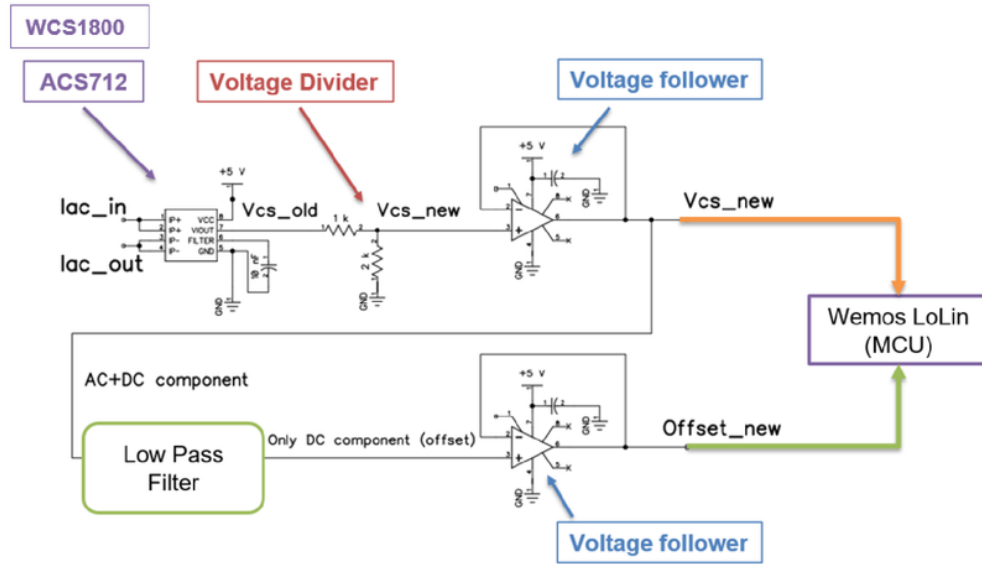


Figure 4.1 Additional circuit of ACS712 and WCS1800

4.1.2 SCT013

Similar to the previous two sensors, the sensor output voltage of SCT013 depends linearly on the instantaneous current as in (4.1). However, the offset is not added internally by the sensor. We must add the offset externally. Hence, we chose the offset to be 1.65 V. It turns out that the variation of the sensor output voltage is only between 0.72 and 2.58 V, already good for the MCU's inputs. Hence, we do not need a voltage divider as for the previous two sensors.

4.1.3 PZEM004T

The output from PZEM004T is UART serial communication in TTL level. It is not an analog voltage level as in the previous three sensors, so we do not need to create any additional circuit. We can get the measured value by using PZEM004T Library [17] to obtain the rms current I_{rms} value directly.

$v_{cs_no_offset}$, we approximate V_{rms} as

$$V_{rms} = \sqrt{\frac{\sum_{n=1}^N v_{cs_no_offset}^2(t_n)}{N}} \quad (4.4)$$

where we sample the voltage N times per second and $t_n = t_0 + n/N$ for some starting time t_0 . The summation in (4.4) could sufficiently represent the integral in (4.3) if N is large enough. In our work, we use $N = 5000$.

From (4.1), we could calculate the desired I_{rms} as

$$I_{rms} = \frac{V_{rms}}{\beta} \quad (4.5)$$

However, the linear current-voltage relation is ideal; in reality the relation is usually nonlinear (e.g., see [15]). In this work we choose to estimate the nonlinear relation between the rms current and voltage with piecewise linear interpolation from the samples collected during calibration because the estimation of the linear parameters can be easily performed by the MCU.

The piecewise linear interpolation estimates the true relation between the rms current and voltage as a piecewise linear function:

$$V_{rms} = \alpha' + \beta I_{rms} \quad (4.6)$$

for some α' and β that depend on the value of V_{rms} and are determined during the calibration process described next.

Now if the MCU sees an rms voltage V_{rms} , it estimates the rms current as

$$I_{rms} = \frac{V_{rms} - \alpha'}{\beta} \quad (4.7)$$

Note that α' is generally non-negative and β positive, due to the nonlinear relation between the rms current and voltage.

As we mentioned before, we use C Arduino language and Arduino IDE to program ESP32 microcontroller. We can obtain I_{rms} by using the following pseudocode.

Algorithm 1 RMS Current Measurement

procedure RMS CURRENT MEASUREMENT

Set N to 5000

Set Gain $\beta = 0.0402$, $\alpha' = 0$

▷ for example

while true **do**

Initialize $sumsq$ to 0

for sample = 1 to N **do**

Get $v_{cs,12bit}$, Offset α_{12bit}

$v_{cs} = v_{cs,12bit} * 3.3 / 4096$

$\alpha = \alpha_{12bit} * 3.3 / 4096$

$v_{cs_no_offset} = v_{cs} - \alpha$

$sumsq = sumsq + v_{cs_no_offset}^2$

$V_{rms} = \sqrt{\frac{sumsq}{N}}$

$I_{rms} = \frac{V_{rms} - \alpha'}{\beta}$

Chapter 5

Gain Calibration and Accuracy Testing Method

We mainly perform two sets of testing. The first set we calibrate each sensor for the gain β , non-offset intercept α' called gain calibration testing and the second set we perform accuracy testing of the current measurement for three units of the ACS712, WCS1800, SCT013, and PZEM004T sensors in manual calibration and for ACS712, WCS1800, and SCT013 in auto-calibration.

5.1 Calibration Method

5.1.1 Manual Calibration

In this *manual* calibration of the sensors. We manually collected the rms current and voltage samples and fitted a linear or multiple linear lines to find a simple explanation of the relationship between the current and voltage as shown in (4.7). Specially, we manually collect the current and voltage samples by adjusting the current loads to a sensor and using volt and current meters to measure the V_{rms} and I_{rms} samples. Then we manually attempted to fit the samples using a linear if possible, but when the fitting error is too high, we used multiple linear lines (a piecewise linear function) instead. Specifically as the result later, we used a single line for the rms current and voltage relation for the ACS712 and SCT013 sensors, but used four lines for the WCS1800 sensor.

For each of the three analog sensors: ACS712, WCS1800, SCT013, we run a calibration test on a randomly selected unit of each sensor. Recall that the PZEM004T sensor do not need calibration for the gain as it already gives the MCU the rms current values.

5.1.2 Auto-Calibration

In this part, we propose a *auto* calibration system that is an improvement of the manual calibration. This is done to improve the calibration accuracy and to allow the

data fitting be completely done by the microcontroller.

From previous chapter, we would like to know the I_{rms} value. So we need to know V_{cs_rms} , gain β , and non-zero intercept offset α' to proceed the I_{rms} calculation process.

In this auto-calibration method, we can take the advantage of equation (4.7) to create an auto-calibration algorithm. We use microcontroller to measure and calculate V_{cs_rms} value from current sensor's output by itself. And we use a keypad that we have mentioned in chapter 3 to help inserting I_{rms} at each step (V_{cs_rms} value).

Hence, we can find gain β , and non-zero intercept offset α' by applying auto-calibration algorithm. The steps of these algorithm are divided in to 6 steps that are described below.

5.1.2.1 First step: Mode Selection

First step in this auto calibration system, the microcontroller is programmed to allow a user to enter into the auto calibration mode. For easy use, we just assigned a pin to be the selecting mode pin which is if that pin has HIGH level (3.3 V), the microcontroller will go to calibration mode. But if we do nothing just let that pin has LOW level (0 V), microcontroller will do a normal current measurement mode. Fig 5.1 show connection of pin 21 and 3.3 V.



Figure 5.1 Mode selection

5.1.2.2 Second step: Inserting No. of step

Second step, the algorithm will require the step value which is the No. of I_{rms} value which we are going to use in this calibration we can insert this value by using a keypad. For example you have 20 different current consumption step so you insert 20 points. The step or point means I_{rms} and V_{cs_rms} of the current sensor's input and output relation graph. Fig 5.2 Diagram of step 2 in auto-calibration operation.

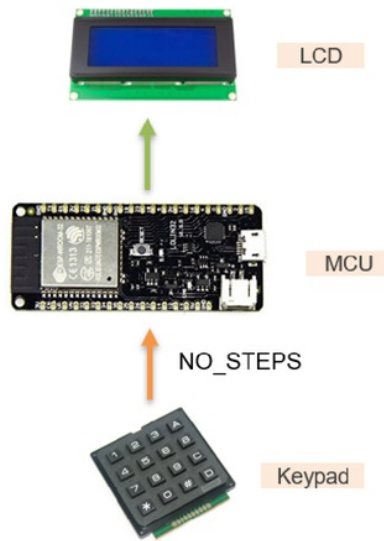


Figure 5.2 Diagram of step 2 in auto-calibration operation

5.1.2.3 Third step: Inserting I_{rms} and reading V_{cs_rms} value

Next, after we define No. of step or No. point in the relation graph. Now, the user can start manually turning on and off some bulb loads to vary the current measured by the sensor then we need to insert I_{rms} that loads consume by using a keypad when finished inserting each I_{rms} value, the microcontroller will automatically read V_{cs_rms} at that current level itself by using algorithm (1) procedure. When finished microcontroller will ask for another I_{rms} so we just turn on or off the loads to consume different current level. We need to do this until all N data points are collected. While we are inserting value, if we have any wrong inserting. We can delete that value and insert the new value

of that point again when it asks for confirmation.

5.1.2.4 Fourth step: Sorting each step's value

After we inserting and reading all step values which are I_{rms} and V_{cs_rms} . The microcontroller will apply bubble sort to sort the point based on I_{rms} value. V_{cs_rms} will be sorted along with its I_{rms} value. So this steps help the user that user do not need to turn on/off loads to consume current respectively from low to high current level. User can turn on/off the loads any format then microcontroller will sort it automatically. I_{rms} after sorting will be in form of low to high value.

```
void bubble_sort(float Irms[],float Vcs_rms[], int n ){
    int i, j, t = 0 ;
    for( i = 0; i < n; i++){
        for( j = 1; j < n - i ; j++){
            if(Irms[j-1] > Irms[j]) {
                swap(&Irms[j-1], &Irms[j]) ;
                swap(&Vcs_rms[j-1], &Vcs_rms[j]) ;
            }
        }
    }
}

void swap(float *a0, float *a1){
    float tmp = *a0 ;
    *a0 = *a1 ;
    *a1 = tmp ;
}
```

Figure 5.3 Code of bubble sorting

5.1.2.5 Fifth step: Applying Ordinary Least Square (OLS)

After all collected I_{rms} were sorted, we start fitting the first line to the first group of the smallest currents via the ordinary least square (OLS) estimates of the line slope and offset. It tries to include as many samples as possible which are fitted by a single line so that the maximum fitting error among all the points is within the pre-specified error threshold. That is, the first three smallest points are fitted by a linear line. If the maximum fitting error of these points is within the error threshold, it adds in the fourth sample and re-estimate the linear line passing through these four points. If the maximum error is still acceptable, it then adds in the next sample and keep on extending the samples fitted by a single line. If after adding a new point to the group and the

parameter re-estimation results in an unacceptable maximum error, the just-added point is removed out of the group and together with the previous point are used to create a new group for the next line. the gain and offset of the previous line is then stored in the non-volatile memory for later voltage-to-current conversion use.

To better understand our auto calibration process, let us introduce some notations. Suppose the N collected and already-sorted rms current and voltage samples are (i_n, v_n) for $n = 1, 2, \dots, N$ where $i_1 < i_2 < \dots < i_N$ and presumably $v_1 \leq v_2 \leq \dots \leq v_N$ since the current-voltage relation is non-decreasing.

The auto calibration algorithm is an iterative procedure, starting with first finding the gain β and offset α' in the linear equation $v = \alpha' + \beta i$ passing through the first two samples (i_n, v_n) for $i = 1, 2$. Since there are only two samples, the gain is $\beta^{(1)} = \frac{v_2 - v_1}{i_2 - i_1}$ and the offset $\alpha'^{(1)} = v_1 - \beta^{(1)} i_1$. Since a line can pass through any two points exactly, the fitting error is zero. Then, the third point (i_3, v_3) is added into the group which now has three samples $(i_n, v_n), n = 1, 2, 3$. Fitting a line now requires estimation of β and α' . We can use the OLS estimation. In general if there are M data points, the estimated gain and offset of the simple linear regression $v = \alpha' + \beta i$ are

$$\beta = \frac{\sum i_n v_n - \frac{1}{M} \sum i_n \sum v_n}{\sum i_n^2 - \frac{1}{M} (\sum i_n)^2} \quad (5.1)$$

$$\alpha' = \bar{v} - \beta \bar{i} \quad (5.2)$$

where the sample averages are $\bar{v} = \frac{\sum v_n}{M}$ and $\bar{i} = \frac{\sum i_n}{M}$.

After the line fitting, we evaluate the fitting performance by starting from the least current point in the group and evaluate the fitting error for this point. We choose our error criteria to start a new line as following:

1. If $i_n < 5$ A, we require the absolute error to be less than the absolute threshold, *AbsThreshold*, which is set to 0.3. The error is defined as

$$e_n = |i_n - \hat{i}_n| \quad (5.3)$$

where the estimated current by the line is

$$\hat{i}_n = \frac{v_n - \alpha'}{\beta} \quad (5.4)$$

2. If $i_n \geq 5$ A, we require the absolute percentage error to be less than the percentage threshold, *PercentThreshold*. The absolute percentage error is defined as

$$pe_n = \frac{|i_n - \hat{i}_n|}{i_n} \times 100\% \quad (5.5)$$

If a point n^* is found to have its fitting error greater than the corresponding threshold, the algorithm starts a new group having two points, $n^* - 1$ and n^* . Then the procedure goes on by adding the third point $n^* + 1$ into the group and doing an OLS estimate for the new line passing through this group of points. Then it checks whether the line fits the three points well enough. If not, the two points $n^* - 1$ and n^* will have its own line and the points n^* and $n^* + 1$ will start a new group. The algorithm keeps on like this until the last point N is fitted by a line, which is in the worst case the last line passes only through the last two points $N - 1$ and N . The fitting procedure is shown in Fig. 5.4.

For each line, we need to store in a lookup table the gain β and offset α' of the line and the range of measured rms voltages (the starting and ending) that we will use this line to calculate the current. Since the lines are connected and the starting point of the first line is always zero, we only need to keep the ending point, $v_{rms,boundary}$, of the interval. This lookup table is stored in the non-volatile storage of ESP32. Moreover, we need to record the number of rows in the lookup table. We can record and read the non-volatile storage by using ESP32 NVS library [18].¹

If we reset the microcontroller, it will read gains β , non-zero intercept offsets α' , $V_{rms,boundary}$, and *number of gain* m of the calibrated current sensor from MCU's non-volatile storage. Then, these value will be used in normal current measurement mode. Algorithm (2) show pseudocode of this step to find β , α' , $V_{cs_rms,boundary}$, and number of gain (m). Fig 5.4 show a flowchart of applying this step.

¹There are other microcontrollers which also have non-volatile storage such as EEPROM.

Algorithm 2 Find *Gain, Offset, V_{cs_rms} boundary*, Number of gain (*m*)

```
procedure APPLYING OLS TO FIND  $\beta$ ,  $\alpha'$ 
  Set ABS_ERROR_ALLOW 0.03 A
  Set PERCENT_ERROR_ALLOW 0.3 %
  Set sumX, sumY, sumXsquare, sumXY to 0
  Set count_n = 1, m = 1, n = 0, start_j = 0
  while n < NO_STEPS do
    sumX += Irms[n]
    sumY += Vcs_rms[n]
    sumXsquare += Irms2[n]
    sumXY += Irms[n] * Vcs_rms[n]
    if count_n >= 2 then
      avgX = sumX / count_n
      avgY = sumY / count_n
       $\beta[n] = (sumXY - (sumX * sumY / count_n)) / (sumXsquare - (sumX^2 / count_n))$ 
       $\alpha'[n] = avgY - (\beta[n] * avgX)$ 
      for int j = start_j to n do
        Irms_back[j] = (Vcs_rms[j] -  $\alpha'[n]$ ) /  $\beta[n]$ 
        Error[j] = Irms_back[j] - Irms[j]
        percentError[j] = abs(Error[j]) / Irms[j] * 100
        if ((Irms[j] < 5) ∧ (abs(Error[j]) > ABS_ERROR_ALLOW)) ∨
        ((Irms[j] >= 5) ∧ (percentError[j] > PERCENT_ERROR_ALLOW)) then
          GAIN[m] =  $\beta[n - 1]$ 
          OFFSET[m] =  $\alpha'[n - 1]$ 
          Vcs_rmsboundary[m] = Vcs_rms[n - 1]
          m++
          count_n = 0
          start_j = n - 1
          n = n - 2
          sumX = 0
          sumY = 0
          sumXsquare = 0
          sumXY = 0
          break
    count_n++
```

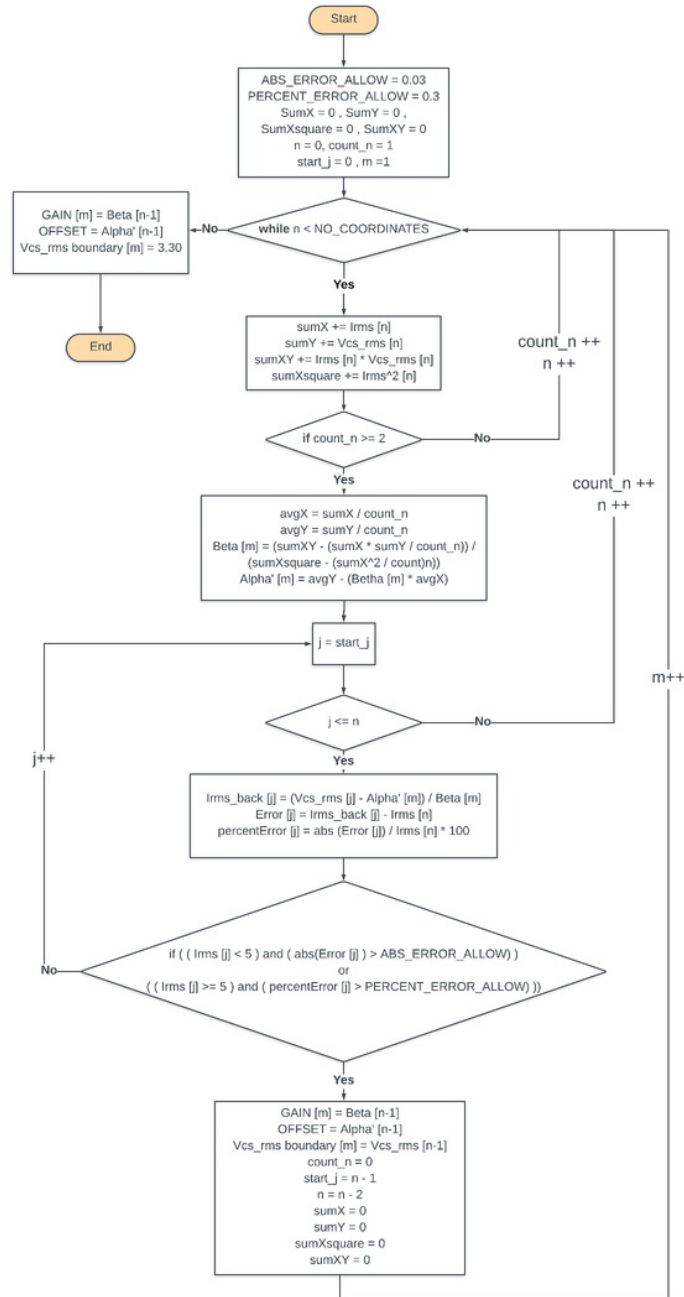


Figure 5.4 Flowchart of applying OLS step

5.1.2.6 Sixth step: Recording parameters after auto-calibration process to non-volatile storage

Finally, after microcontroller applying OLS and got all gains β and non-zero intercept offsets α' also V_{cs_rms} boundary, all of these value will be recorded in non-volatile storage of ESP32. Moreover, it will record No. of gains which is it will be used to read β , α' , V_{cs_rms} boundary in the normal measurement operation. We can simply record and read this storage by using ESP32 NVS library [18]. It is not just only ESP32 which can use this algorithm, for any other microcontroller which have non-volatile storage such as EEPROM also can similarly use all above auto-calibration algorithm.

If we reset the microcontroller, next time it will read gains β , non-zero intercept offsets α' , V_{cs_rms} boundary, and *No.ofgain* of the calibrated current sensor from its non-volatile storage. Then, these value will be used in normal current measurement mode. Fig. 5.4 show a brief flowcharts of this auto-calibration algorithm.

```
Serial.println("[NVS] set object to NVS") ;
NVS.setObject( "Gain", &GAIN, sizeof(GAIN) );
NVS.setObject( "Offset", &RMS_OFFSET, sizeof(RMS_OFFSET) );
NVS.setObject( "Vmargin", &MARGIN_I_Vrms, sizeof(MARGIN_I_Vrms) );
NVS.setInt("No_m", m);

Serial.println("[NVS] get object from NVS");
float* get_GAIN = (float*)NVS.getObject("Gain");
float* get_OFFSET = (float*)NVS.getObject("Offset");
float* get_VMargin = (float*)NVS.getObject("Vmargin");
int NO_RANGE = NVS.getInt("No_m");
```

Figure 5.5 Code of recording and reading from non-nolatile memory

5.2 Accuracy Testing Method

For both manual and auto-calibration method, we use same manner in accuracy testing. In this test, We vary constant testing loads current up to 20 A in 60 steps. We test 4 different sensors (ACS712, WCS1800, SCT013, PZEM004T) for manual calibration . Each type of sensor, we use 3 units. Then, we average them to get final value. But the gain calibration is performed on only one randomly selected unit then we utilize the resulted gain for the other 2 units.

Not that. For manual calibration, This may cause some small errors since different units may have a slightly different gain. But in auto calibration, we calibrated each unit independently.

For accuracy testing in auto-calibration, we test only 3 analog output current sensors for (ACS712, WCS1800, SCT013). we use both 20 and 50 points calibration to test with 60 steps current. We also find fitting error compared to testing error.

Chapter 6

Results and Discussion

6.1 Gain Calibration Results

6.1.1 Gain Calibration Results: Manual Calibration

In the manual calibration, the gain of the current sensor or the linear relation between V_{cs_rms} and I_{rms} and non-zero intercept offset will be a constant number. In this case, the gains β of SCT013 and ACS712 are estimated to be 0.0328 and 0.0402 respectively, with R^2 almost one and they have zero intercept as shown in Fig. 6.1 and Fig. 6.2. However, the relation between V_{cs_rms} and I_{rms} of WCS1800 is not quite linear which is the slope (gain β) is decreased when I_{rms} increased. Therefore, we can arbitrarily choose to fit the relation with lines. However, we can still fit a piecewise linear function quite nicely, where we divided I_{rms} into 4 ranges as shown in Fig. 6.3

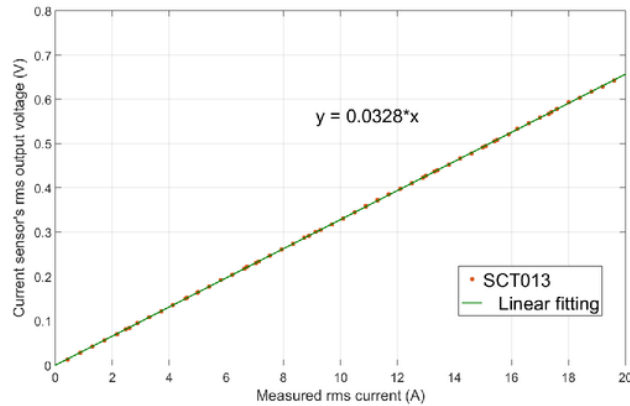


Figure 6.1 SCT013 manual calibration ($R^2 = 1$)

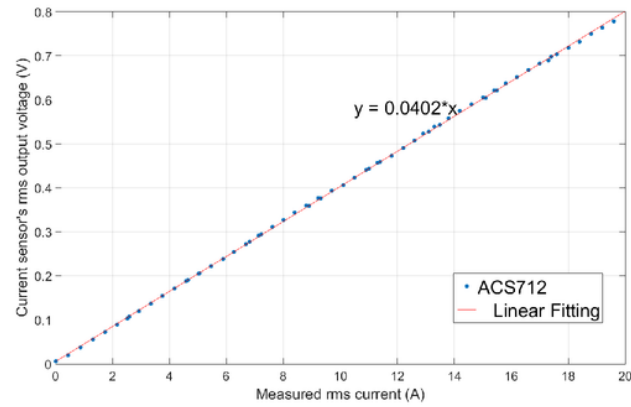


Figure 6.2 ACS712 manual calibration ($R^2 = 0.9997$)

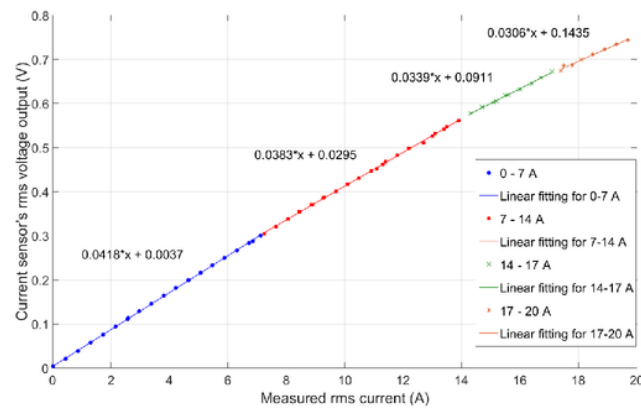


Figure 6.3 WCS1800 manual calibration ($R^2 = 0.9998, 0.9996, 0.9972, 0.9958$)

6.1.2 Gain Calibration Results: Auto-Calibration

Table 6.1 Number of gain of current sensors

Current Sensor	50 points			20 points		
	No.1	No.2	No.3	No.1	No.2	No.3
SCT013	8	6	6	4	4	4
ACS712	11	9	9	8	8	7
WCS1800	10	11	11	7	9	9

Table 6.1 show the Number of gains when we apply auto-calibration algorithm for 3 different analog low-cost current sensors. We tested 3 unit for each type of current sensor.

As we know that relation of SCT013 is linear with R^2 very close to one so this type of current sensor has the least number of gain compared with another current sensor. The gain result of this sensor is around 0.031-0.034 mV/A.

The result also show that ACS712 has number of gain more than SCT013 because it has lower R^2 value. The gain result of this sensor is around 0.031-0.047 mV/A but most of them vary near 0.040 mV/A.

From the 50 points calibration results of WCS1800, The number of gains is the most. It might cause from the relation between V_{cs_rms} and I_{rms} of WCS1800 is not quite linear that is the gain decrease when current increase. We can see that even in manual calibration we need to divided and defined the gain into 4 ranges. When current increase, the gain is start from 0.043 and continuously decrease to 0.024 mV/A.

We can see that for all of the current sensor, the number of gains for 50 points calibration will be more than 20 points calibration because if we have more points to calculate the linear equation, it will be sure that the microcontroller will produces more accurate gains and different value of gains and non-zero offset intercept value. One interesting thing of this result is, the 50 and 20 points calibration will not give any different in number much for ACS712. It might be because of the gain about 8-9 gains is enough to fit the piecewise function. The following value is the example value of WCS1800's gains and non-zero offset intercept when calibrated with 20 points. In Fig. 6.4 show the example graph of relation between V_{cs_rms} and I_{rms} of one of WCS1800 current sensor.

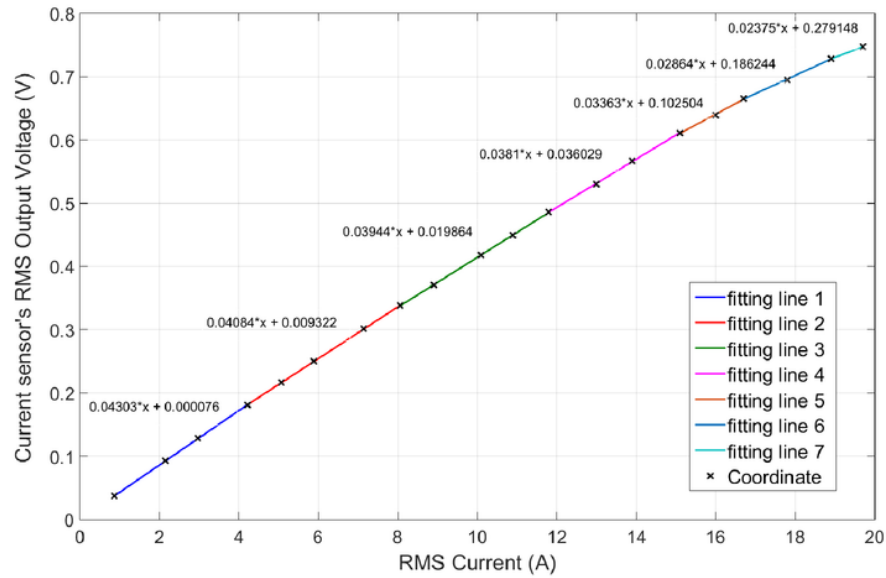


Figure 6.4 Example of WCS1800's gains when applied auto-calibration algorithm

Table 6.2 Example of gain, offset, and boundary of one of WCS1800

$V_{CS_{rms}}$ (V)		Gain (mV/A)	Offset (V)	R^2
Starting point	Ending point			
0	0.181	0.04303	0.000076	0.99997
0.181	0.338	0.04084	0.009322	0.99996
0.338	0.486	0.03944	0.019864	0.99991
0.486	0.611	0.03810	0.036029	0.99954
0.611	0.665	0.03363	0.102504	0.99744
0.665	0.728	0.02864	0.186244	0.99924
0.728	3.30	0.02375	0.279148	1

6.2 Accuracy Results

6.2.1 Accuracy Results: Manual Calibration

Fig. 6.5 shows the measurement error by testing 4 type of sensors. From the figure,

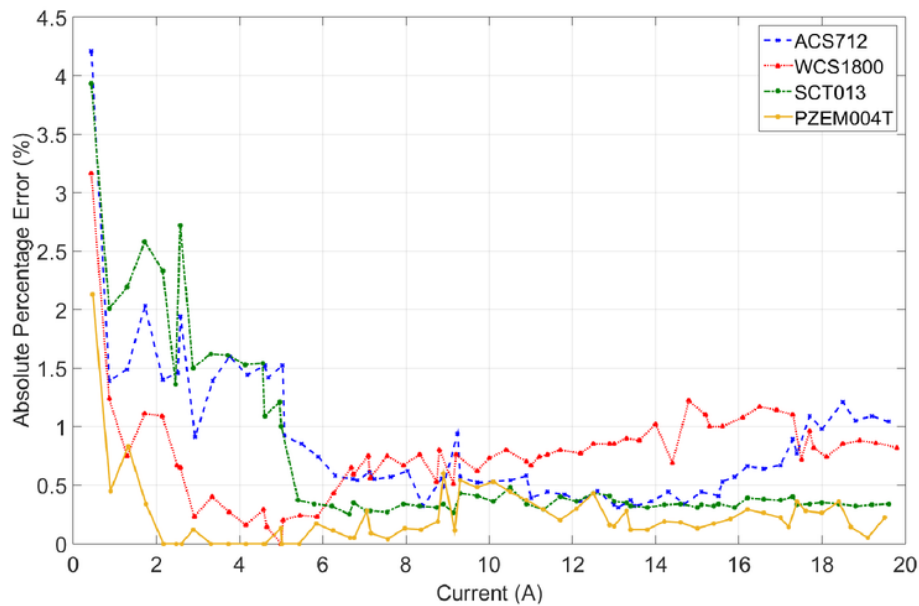


Figure 6.5 Measurement accuracy error of 4 different current sensors

PZEM004T's result and SCT013's result above 5 A current is very similar and very accurate which are error $< 0.5\%$. Also, these 2 sensors have similar price and it is not expensive compared to their performance in this range. So these 2 sensors are very good option for measuring current higher than 5 A.

However, They have some difference which are when install PZEM004T sensor we need to break a measured wire at a connection point and put the measured wire through the iron core's hole before connect the wire back. But for SCT013, we can split the iron core then just easily clamp on the measured wire. Besides, for current about 1-5 A, SCT013 produce high error result which is $> 1\%$ (if calculate absolute error it can be acceptable that is for range < 1.5 A error < 0.03 A, range 1.5-2.5 A error < 0.05 A, and 2.5-5 A error < 0.07 A) but PZEM004T still give the same percentage error which is $< 0.5\%$ (absolute error < 0.01 A throughout the range). So PZEM004T is better for measure current in the lower range.

ACS712 is a very low-cost current sensor. From the graph in Fig. 6.5, at the low current, this sensor give high error (but for absolute error, it is still small that is < 0.05 A). Anyway, the error will decrease when current is higher. When measured current is

about 5-11 A, the error is decrease to be equal 0.5-1 % and when current in 11-15.5 A range, the error is more decrease to be < 0.5 %. But for the higher current 15.5-18 A, the error is increase to be 0.5-1 %. And the very high current 18-20 A, the error slightly more than 1 %. It occurs because as Fig. 6.2, the slope (gain) at very high current (18-20 A) is lower than the using gain. So at that range, it can be more accurate if we use a new gain but also it is not convenient and cost more time to do. Thus, this sensor can give good result at 5-18 A (error < 1 %). As this sensor give low error with the ultra-low price so we can say that this sensor is extremely worthy. But if you have more budget, PZEM004T and SCT013 will be the better choice because they give the better accuracy while still cost acceptable budget. However, ACS712 current sensor is a good option to use in ultra low-cost work with can allow some acceptable error. So it good for a small project that does not need the very accurate measurement result.

For the last one, WCS1800. Fig. 6.5 shows that the error result is more than any other current sensor in almost all current range except current lower than 6 A that the error is about 0.5-1 % for current 1-2.5 A (absolute error < 0.02 A) and error < 0.5 % for current 2.5-5 A (absolute error < 0.01 A) which is better than ACS712 and SCT013. Also, the error is slightly better than ACS712 in 18-20 A. So from the overall result, we can tell that this sensor did not give the better result than the other compared sensors based on this test situation. The error might cause from the gain which can not be exactly fitted because the changing of the gain. But if we fit many more gain, it might give the better result but also spend more time which is not appropriate to do in practical work. The good advantage of this sensor is the installation, we just put the measured wire through the sensor's hole like PZEM004T so it more comfortable than ACS712 installation.

6.2.2 Accuracy Results: Auto-Calibration

In this topic, we perform the test by using 3 approaches for collecting the accuracy result. First, we test the accuracy of current sensor with manual calibration that we already tested and have the result from the past subsection. Second and third approach, we apply auto-calibration algorithm to microcontroller by using 50 and 20 points then we test the accuracy of sensors. In this test, we vary constant testing loads current up to

Table 6.3 Percentage error of fitting error

Current Sensor	Current range (A)	Average Absolute % Error		
		50 points	20 points	Manual
SCT013	0-20	0.22	0.25	0.42
	1-5	0.29	0.32	0.64
	5-20	0.13	0.15	0.2
ACS712	0-20	0.29	0.39	0.86
	1-5	0.33	0.41	1.14
	5-20	0.2	0.26	0.59
WCS1800	0-20	0.26	0.31	0.59
	1-5	0.3	0.31	0.75
	5-20	0.23	0.28	0.32

Table 6.4 Percentage error of testing Error

Current Sensor	Current range (A)	Average Absolute % Error		
		50 points	20 points	Manual
SCT013	0-20	0.23	0.35	0.73
	1-5	0.29	0.72	1.77
	5-20	0.12	0.15	0.36
ACS712	0-20	0.36	0.51	0.86
	1-5	0.41	0.63	1.51
	5-20	0.25	0.37	0.62
WCS1800	0-20	0.36	0.55	0.76
	1-5	0.29	0.46	0.48
	5-20	0.24	0.47	0.78

20 A. We test 3 different sensors (ACS712, WCS1800, SCT013). Each type of sensor, we use 3 units. Then, we average them to get average absolute % error value. Finally, we compare them together to see how the result will be.

Table 6.3 shows the fitting error which is the value of error when we use obtained β gain and α' non-offset intercept to calculate I_{rms} back by using V_{cs_rms} that we got while calibration process. We can see that almost error in 50 point calibration will be not more than 0.3 % as the defined error condition.

As the result in Fig. 6.6 and Table 6.4, we can see that SCT013 is very accurate for all range after apply 50 points auto-calibration algorithm that is % error < 0.3 %. For 20 points calibration at low current, % error seem to be a bit high but it is still good enough. Moreover in current > 5 A, the % error of both 20 and 50 points calibration

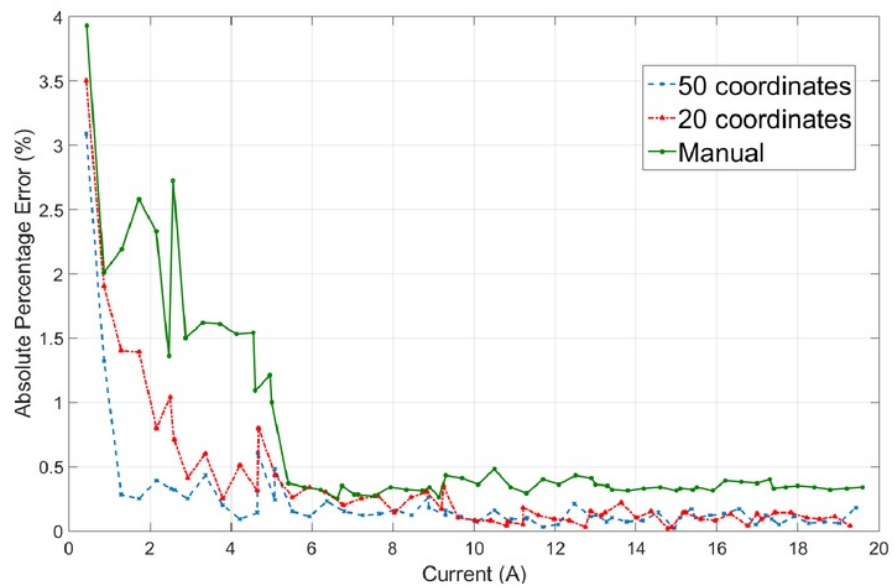


Figure 6.6 SCT013 accuracy test result

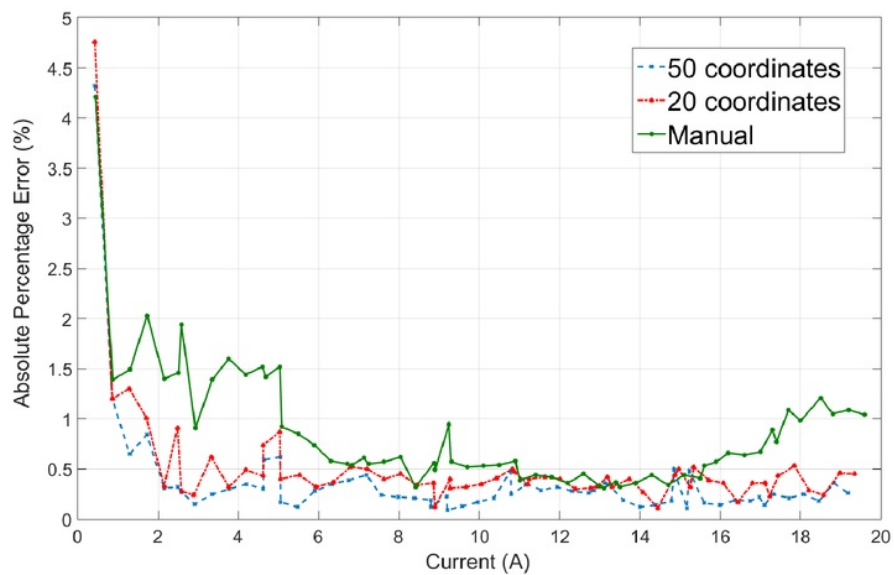


Figure 6.7 ACS712 accuracy test result

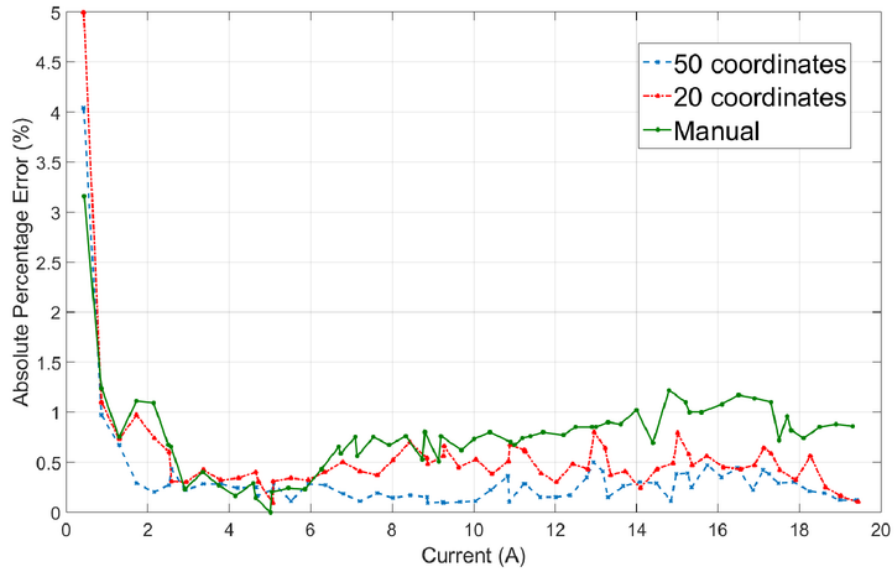


Figure 6.8 WCS1800 accuracy test result

have no different. It may cause from the relation between V_{cs_rms} and I_{rms} is so linear which we can see from Fig. 6.1 that R^2 almost one.

Fig. 6.7 and Table 6.4 show ACS712's accuracy result that if we apply auto-calibration algorithm the result will be much better than manual calibration especially for very low current. And normally, this sensor's gain gradually decreased when it measure very high current because of the saturation so it cause high % error. But as in the result, this calibration algorithm can solve this problem by decreasing the gain as it need to be. From Table 6.4, we can say that 20 points calibration is enough to make this sensor give a very acceptable accuracy that is the % error equal 0.5 %.

For WCS1800's accuracy result, the result in Fig. 6.8 and Table 6.4 show that when we apply auto-calibration algorithm the % error is decreased in almost all range except some range which the manual calibration already give accurate measurement. We can see that 50 and 20 points calibration is obviously different. It might be because of this current sensor has the relation between V_{cs_rms} and I_{rms} quite not linear as we have mentioned before so when we apply more point in the calibration the result is much

better. But anyway from Table 6.4, the average % error still acceptable for 20 point calibration which is % error is about 0.5 % only for all of the current range.

From all accuracy test result in Table 6.4, The result show that if we apply auto-calibration algorithm, it can improve accuracy of analog current sensor to be better than manual calibration as we prior expected. And we can say that if we use 50 points in auto-calibration algorithm the result will be better than using 20 points calibration but it might does not have much differences which we can see that from 20 points calibration result give very good and acceptable accuracy. So 20 points calibration is the most suitable to use in real work because it does not require so many steps of consuming current and the time of calibration is much less than 50 point calibration which it improve accuracy from 20 point calibration not much.

Chapter 7

Conclusion

7.1 Summary of calibration and testing

The first part of this work, we perform a measurement accuracy comparison by testing 4 different low-cost current sensors. We also discussed about 2 more conditions to consider in selection these current sensors which are price and difficulty in installation. When we consider about price and accuracy result together, we can rank from the best to the worst performance (based on this test situation) as following. PZEM004T, SCT013, ACS712 and WCS1800. The results show that PZEM004T give the best performance with the good price also it can measure voltage and power which can be further used. SCT013 take the second place because of its very good performance with acceptable price. Follow with ACS712, it give an acceptable result with ultra-low price so it is extremely suitable for a small project. The last one is WCS1800, which is the most expensive sensor among these 4 sensors here, its overall result does not gives a good percentage measurement error and also it has the most difficult to use because of its gain change when measured current range is changed.

For the difficulty in installation, the most comfortable in installation is SCT013 because we can just split core and clamp the sensor on the measured wire so this sensor is suitable with the work or project that does not want to turn off the power supplying or circuit breaker or disconnect any wire of electrical system. Next, the slightly more difficult to install is PZEM004T and WCS1800 because we need to break a connection point of electrical system and put the measured wire through their iron core. Then, we will be able to connect the wire back. And the most difficult to install is ACS712 because we need to break the circuit of the measured wire and connect sensor in series. So this sensor suitable with a small project that does not need many current sensors to be installed. Therefore, PZEM004T is the best option if your work can allow to turn-off the circuit breaker of the measured wire for current sensor installation.

The second part, we created an auto-calibration algorithm which can apply to analog

output current sensor for improving accuracy in current measurement and convenience in the real work that needs to calibration many units of sensor such as building energy monitoring. So we focus on current from 0-20 A that air conditioner may consume. We used ESP32 wifi-microcontroller to operate both in calibration mode and normal measurement mode. In the calibration process, we used ordinary least square method and defined error condition to get a piecewise linear function. While we calibrated the sensor we used many loads to consume current from 0-20 A also we used this loads in normal accuracy test. We have 2 main results to be discussed which are calibration result and accuracy result.

From the calibration result, we can conclude that the gain of SCT013 and ACS712 is less than WCS1800. Because normally, relationship between $V_{cs,rms}$ and I_{rms} of WCS1800 is quite not linear compared with SCT013 and ACS712 which seem to be linear.

And from accuracy result, we can say that this calibration operation can improve the accuracy of analog output current sensor obviously from 0.7-0.9 % error in manual calibration to 0.2-0.4 % error in auto-calibration. And the more calibration coordinate we apply, the more accuracy we get. Anyway, 20 coordinate is already accurate and very good enough to use in real work. So we might do not need to apply more coordination points in the calibration because it cause more time.

7.2 Suggesting for future works

In the first work we only focus on current measurement of the current sensor module which available in the market nowadays. However, the energy IC might also interesting to do but require much more hardware and circuitry skills to create measurement module. Then, it can be massively constructed according to designed circuit by any hired company.

Although our auto-calibration can improve accuracy result of current sensor, we just only use a simple mathematics equation. If any future work might apply any neuron network or artificial intelligence. It might give a better result. Moreover, our proposed method is just a semi auto-calibration that still need the human involve in the calibration process to insert the some value by using a keypad. Future work might

create the full auto-calibration by utilize some serial communication from some high grade reference meter connect directly with microcontroller such as RS232 to provide I_{rms} for microcontroller and use many relays to turn on/off load automatically by microcontroller.

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Appendices

Appendix A

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- Ruengwit Khwanrit, Somsak Kittipitykul, Jasada Kudtongngam and Hideaki Fujita, “Accuracy Comparison of Present Low-cost Current Sensors for Building Energy Monitoring”, *9th International Conference on Information and Communication Technology for Embedded System (IC-ICTES)*, 2018

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